

## TCW4 CANopen

### CANOPEN ABSOLUTE MULTI-TURN MODULAR SENSOR

Sensata-BEI Sensors' TCW4 sensors provide absolute multi-turn measurement with a CANopen output in an over-molded, modular package that offers design flexibility and protection from the environment.



#### Features

- With its two-part design, the TCW4 CANopen absolute multi-turn offers maximum flexibility for installation
- Rugged and excellent resistant to shock and vibration
- Robust, proven magnetic technology
- Environmentally resistant, IP 67 standard (IP69K option)
- Extended operating range from -30° C to 85° C
- Uses universal supply 5 to 30 VDC CAN open output
- Available resolution 12 bits per turn by 16 bits of turns counting
- Variety of magnet holders available
- Standard PVC cable with SUBD9 connector

### **Applications**

- Factory Automation
- Process Automation





#### Mechanical

Terminations	PVC Cable with SUBD9 connector			
Housing	Macromelt PA638			
Weight	0,150 kg			

#### Electrical

Output Function	CANopen				
Minimal Cycle Time	< 400μs				
Resolution	Multi-turn 12 bits per turn and up to 16 bits of turns counting				
Accuracy	+/-0.3% on 360°				
Repeatability	+/-0.1% on 360°				
Supply Voltage	5 to 30 Vdc				
Start-up	<1 s				
Current Requirements	< 40mA				
Protection	Overvoltage Protection: Yes Reverse Polarity Protection: Yes Short Circuit Protection: Yes				
ЕМС	IEC 61000-4-2 Electrostatic discharge (ESD) 4 kV, 8 kV IEC 61000-4-3 Electromagnetic fields 10 V/m (80MHz - 1GHz), 3V/m (1.4GHz - 2GHz), 1V/m (2GHz - 2.7GHz) IEC 61000-4-4 Electrical fast transients (burst) 1 kV IEC 61000-4-6 Conducted disturbances, induced by RF-fields 10 Veff.				



## **Programmable Parameters**

**Resolution:** Defines the resolution per revolution (0 to 4 096).

Transmission Speed: Programmable from 10kBaud (1 000m) to 1 Mbaud (25 m); value per default: 20 Kbaud.

Address: Defines the software address of the encoder on the bus (1 to 127, Value per default : id = 1).

**Direction:** Defines the direction of count of the sensor.

**RAX:** Defines the value of the current position (with the shaft held stationary)

#### **Communication Modes**

**Sensor configuration**: Reading/Writing of the sensor objects dictionary (SDO mode).

3 modes are available to interrogate the encoder position/speed:

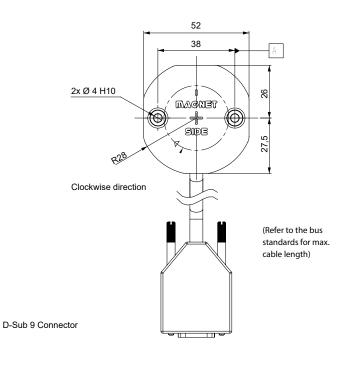
**CYCLIC Mode:** The sensor transmits its position in an asynchronous manner. The frequency of the transmission is defined by the programmable cyclic timer register from 0 to 65 535 ms.

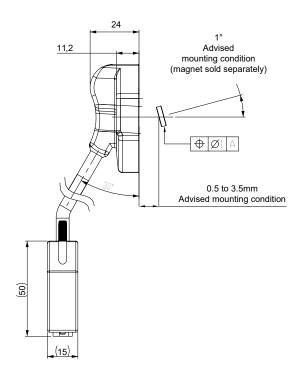
**SYNCHRO Mode:** The Sensor transmits its position on a synchronous demand by the master.



All Dimensions are in millimeters.

Shaft system with magnet to be ordered separately (see Accessories).





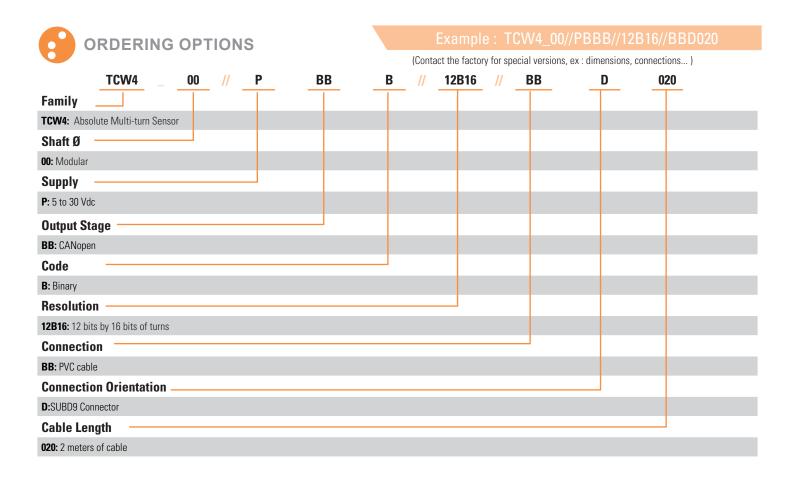




	N.C	CAN LOW	CAN GND / OV	N.C.	N.C.	<b>0V</b>	CAN HIGH	N.C.	5/30Vdc	Ground	
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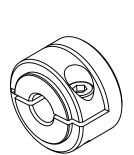
Stray magnetic fields can interfere with accuracy and repeatability of the signal.

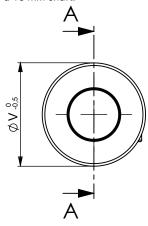


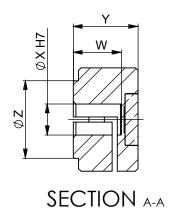


# Female magnet support + Magnet 8810/013 Ordering p/n : M9105/Kxx

KXX: Where XX is the shaft mounting diameter in mm. Standards are 06, 08, 10, 11, and 14 mm. i.e M9105/K10 mounts to a 10 mm shaft.

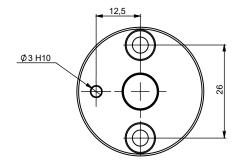


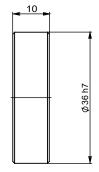


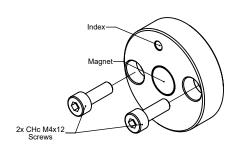


	M9105/K06	M9105/K08	M9105/K10	M9105/K11	M9105/K14
X	06 H7	08 H7	10 H7	11 H7	14 H7
V	20	20	26	26	29
W	9,3	9,3	10	10	10
Υ	12,5	12,5	14	14	14
Z	15	15	15	15	18

# Frontal magnet support + Magnet 8810/013 Ordering p/n : M9105/F26

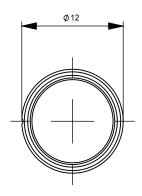


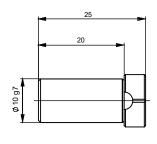




#### Male magnet support + Magnet 8810/013

Ordering p/n: M9105/M10-01

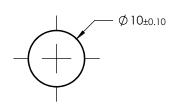


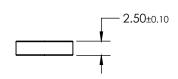




#### Magnet Ordering p/n: 8810/013







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